

AVACS*

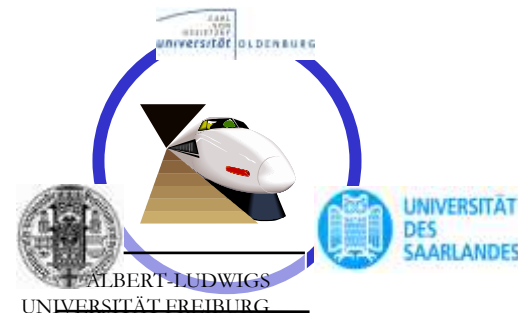
Automatic Verification and Analysis of Complex Systems

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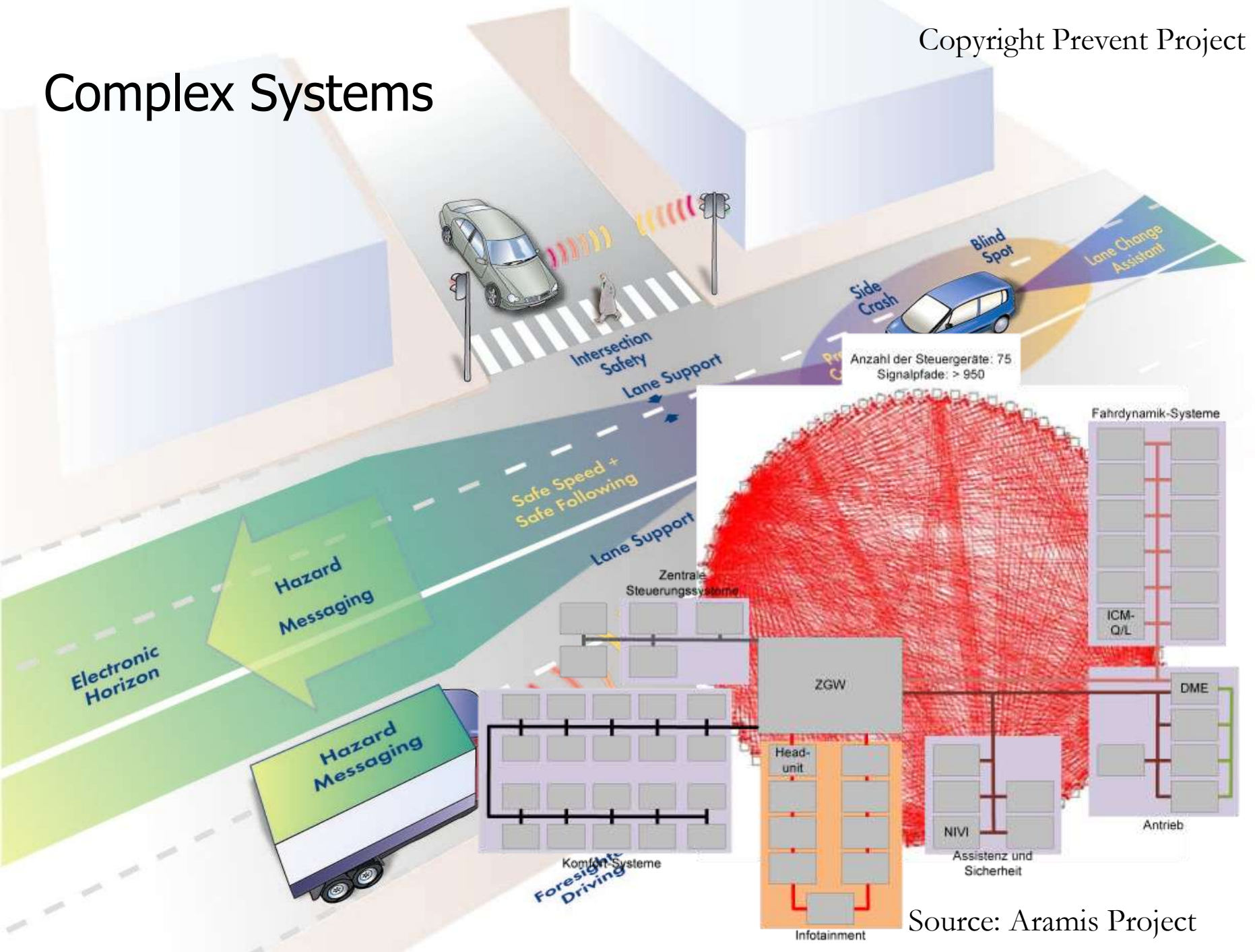
*www.avacs.org

Transregional Collaborative Research Center
funded by the German Science Foundation SFB-TR 14

1.1.2004 – 31.12.2015 total funding \approx 30 Mill €



Complex Systems



The Application Context

- Complex Embedded Systems are **key enablers for safe** flight and safe ground **transportation**
- **Exponential growth in system complexity is a challenge for quality assurance**
- **AVACS contributes to** meeting forthcoming requirements of pertinent **safety standards** on use of **formal analysis methods**
- **Methods and tools** cover large class of “cyber physical systems” seen to be **highly relevant for addressing societal challenges** (health, security, green mobility, ...)



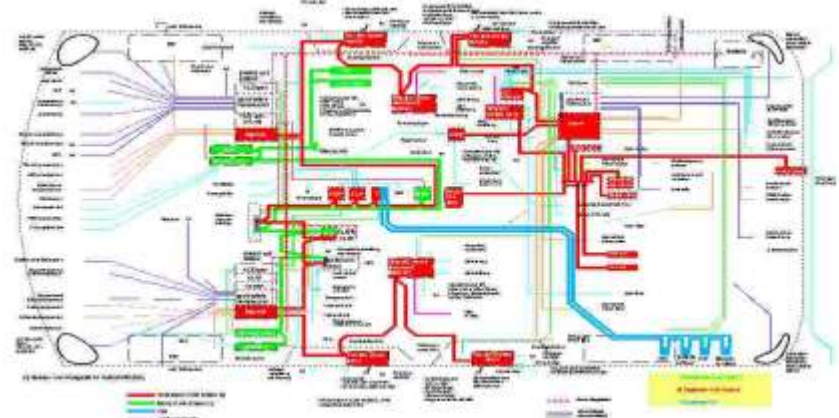
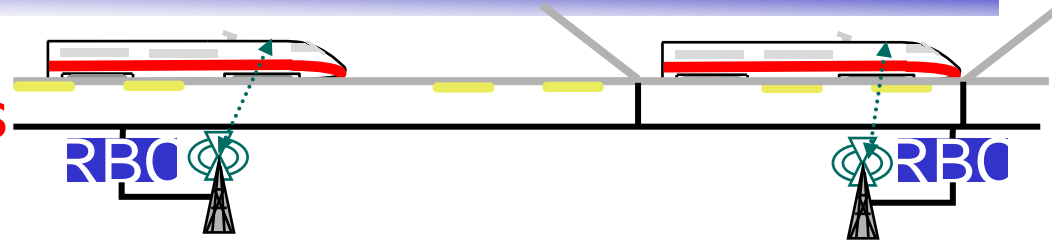
Automatic Verification of Complex Systems: Models

- Extremely **Heterogeneous Model Space**

- Systems of Systems
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- Cycle Accurate models of HW

- Comprehensive and Scalable Verification requires

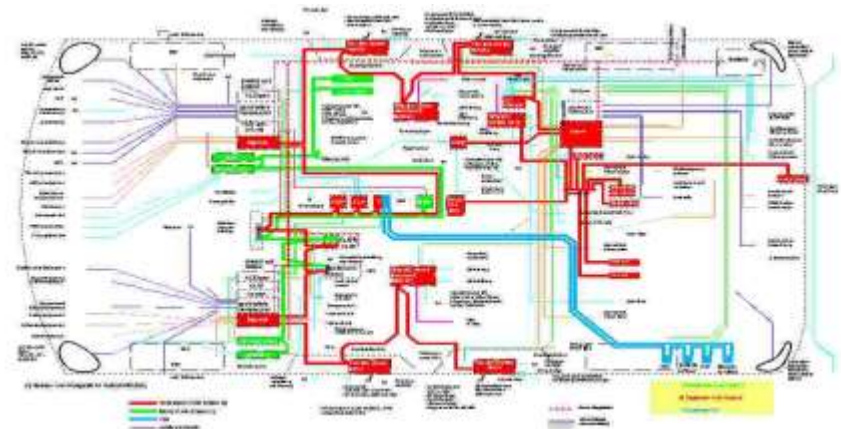
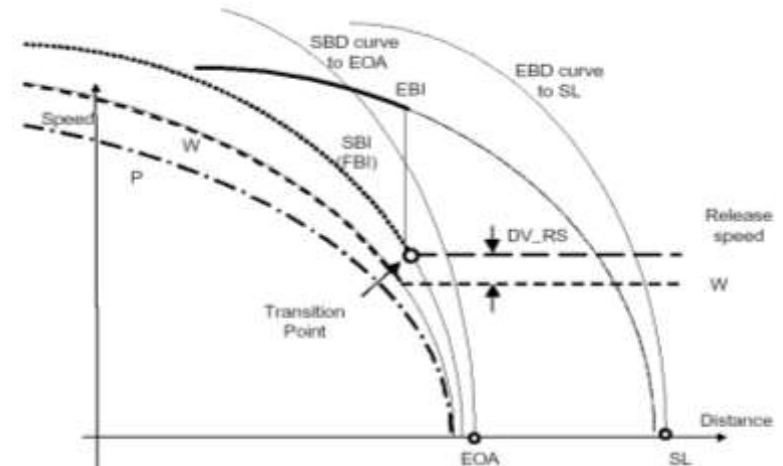
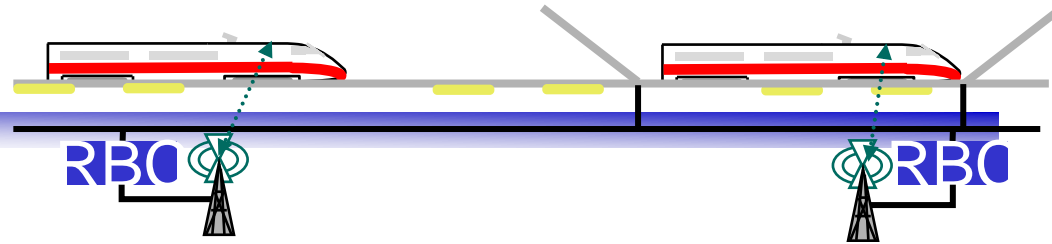
- **Relating Models** at different Design Levels
- Identification of typical **model characteristic**

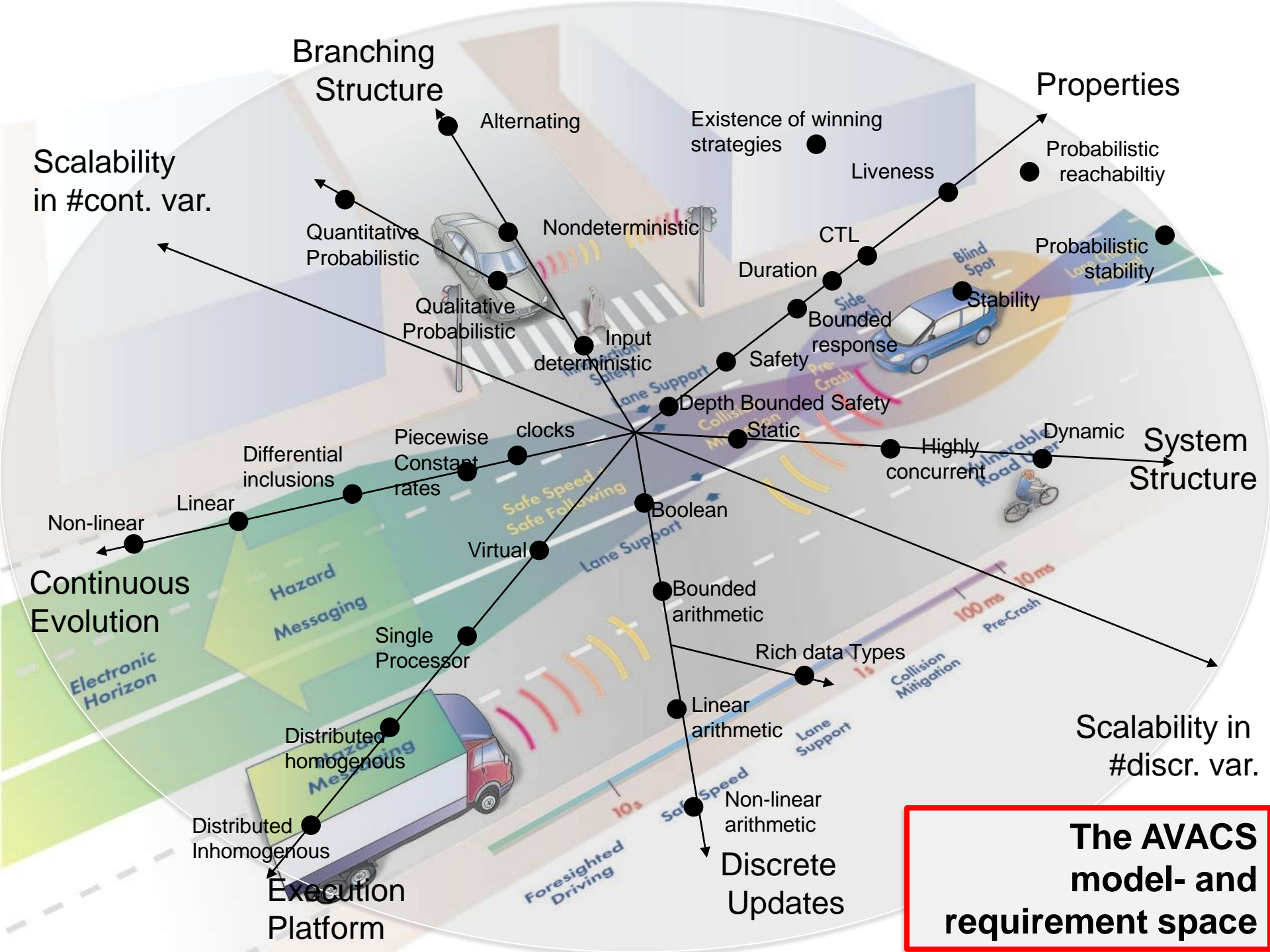


Requirements

Heterogeneous Requirement Space

- **Reliability**
„probability of total a/c failure is less than 10^{-9} per flight hour“
- **Coordination**
“Crossing will grant access if secured“
- **Local Control**
“The train will never run faster than permitted speed“
“enforce brake profile“
- **Real-Time**
“When receiving unconditional emergency stop message the train shall be tripped within 5 msec“
“Brake curve control task activated every 30 msec“





The AVACS model- and requirement space

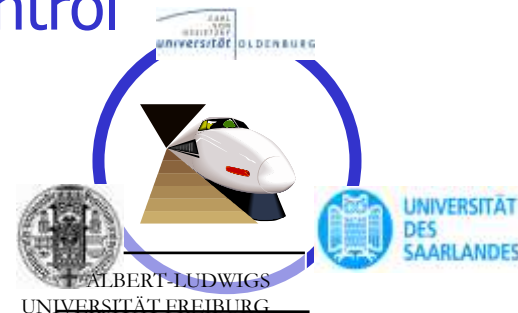
The AVACS Vision

To Cover the Model- and Requirement Space of
Complex Safety Critical Systems

with **Automatic** Verification Methods

Giving Mathematical Evidence
of Compliance of Models

To Dependability, Coordination, Control
and Real-Time Requirements



AVACS Competence Layers

Complex Systems
Embedded Transportation Applications

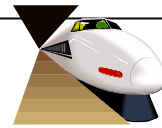
Models of Complex Systems
real-time – hybrid – distributed systems – system of systems

Combining V&A Technology
 $(x_1 \wedge x_2 \wedge \dots \wedge x_n \text{ for } s)$
 $x_j \in \text{V\&A core technologies}, s \in \text{systems}$



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OLDENBURG



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DES
SAARLANDES

V&A Core Technologies
Abstraction – Decision Diagrams – Constraint Solving – Heuristic Search
Linear Programming – Model Checking – Lyapunov Method
Abstract Interpretation – SMT – Decision Procedures

Research
Areas

R

Real-Time

H

Hybrid

S

Coarse
Grain
System
Structure