Sven Schewe

University of Liverpool

AVACS Autumn School, October 2<sup>nd</sup>, 2015

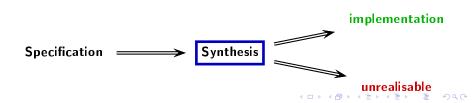
### A Modest Goal

• obtain correct systems ....

### A Modest Goal

- obtain correct systems
- ... without doing anything.





# **Applications**

- Detection of inconsistent specifications
- Partial design verification (Early error detection)
- Error localisation
- Automated prototyping

Specification

ATL, ATL\*, CL alternating-time  $\mu$ -calculus



Specification & Architecture

+ CTL, LTL, CTL\*  $+ \mu$ -calculus

Requirement: The scientist can get as much coffee as she likes.

 $\mathsf{ATL}^*$ :  $\langle\langle scientist \rangle\rangle \square \diamondsuit \mathsf{get}_{coffee}$ 



Specification

ATL, ATL\*, CL alternating-time  $\mu$ -calculus



Specification & Architecture

+ CTL, LTL, CTL\*
+ \( \mu \)-calculus

Lenvironment I

want coffee get coffee

brew! brewing group

grind! b\_info

g\_info

grinder

Requirement: The scientist can get as much coffee as she likes.

LTL:  $\square$  (want<sub>coffee</sub>  $\rightarrow \diamondsuit$  get<sub>coffee</sub>)

 $\mathsf{CTL} \colon \forall \Box \ (\mathsf{want}_{\mathit{coffee}} \to \forall \diamondsuit \ \mathsf{get}_{\mathit{coffee}})$ 



sensor

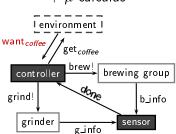
Specification

ATL, ATL\*, CL alternating-time  $\mu$ -calculus



Specification & Partial Design

+ CTL, LTL, CTL\* +  $\mu$ -calculus



Requirement: The scientist can get as much coffee as she likes.

 $\mathsf{LTL} \colon \ \Box \ (\mathsf{want}_{\mathit{coffee}} \to \diamondsuit \ \mathsf{get}_{\mathit{coffee}})$ 

 $\mathsf{CTL} \colon \forall \Box \ (\mathsf{want}_{\mathit{coffee}} \to \forall \diamondsuit \ \mathsf{get}_{\mathit{coffee}})$ 



Specification

ATL, ATL\*, CL alternating-time  $\mu$ -calculus



Specification & Partial Design

+ CTL, LTL, CTL\* +  $\mu$ -calculus

| environment | want coffee | get coffee | brew! | brewing group | grind! | binfo

Automata-Theory

Constructive Non-Emptiness Games



# The birth of the synthesis problem

Alonzo Church Cornell University Summer Institute of Symbolic Logic 1957

Given a requirement which a circuit is to satisfy, we may suppose the requirement expressed in some suitable logistic system which is an extension of restricted recursive arithmetic. The synthesis problem is then to find recursion equivalences representing a circuit that satisfies the given requirement (or alternatively, to determine that there is no such circuit).

# Church's Solvability Problem



### Church's Solvability Problem

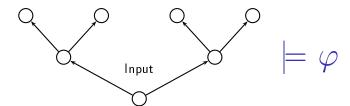
1963

Given: an interface specification

(identification of input and output variables)

and a behavioural specification arphi

Sought: an implementation ( $\mathit{Input}^* \to \mathit{Output}$ ), satisfying  $\varphi$ 



# Church's Solvability Problem



### Church's Solvability Problem

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Given: an interface specification

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## Church's Solvability Problem



### Church's Solvability Problem

1963

Given: an interface specification

(identification of input and output variables)

and a behavioural specification arphi

Sought: an implementation ( $Input^* \rightarrow Output$ ), satisfying  $\varphi$ 

 $\exists \mathsf{Proc} \ \forall \mathsf{Env} \ | \ \mathsf{Proc} \models \varphi$ 

## Part I

But how? History and Simplicity of Synthesis

### Synthesis through the ages

- 1963 Church's solvability problem1969 Büchi and Landweber, finite games of infinte duration
- 1969 Rabin's solution based on deterministing  $\omega$ -automata

```
Algorithms
LTL

1989 Pnueli and Rosner

2005 Kupferman and Vardi "Safraless"

2007 S and Finkbeiner "Büchiless"
```

```
Tools

2009 Filiot, Jin, and Raskin (Antichain)
2010 Ehlers (BDD)
...
```

# Algorithms

in the vicinity of synthesis

#### Tree Automata

- Projection
- Narrowing / information hiding

simple simple

#### Word Automata

determinisation

difficult

# Algorithms

in the vicinity of synthesis

#### Tree Automata

- Projection
- Narrowing / information hiding

simple simple

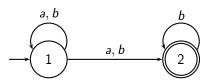
#### Word Automata

determinisation

difficult

But why is it difficult?

### Finite and Büchi Automata



#### Finite Automata

interpreted over finite words

here: over  $\Sigma = \{a, b\}$ 

run: start at some initial state

stepwise: read an **input** letter, and

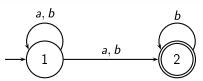
traverse the automaton respectively

accepting: is in a final state after processing the complete word

language: words with accepting runs

here:  $\Sigma^* \setminus \{\varepsilon\}$ 

### Finite and Büchi Automata



#### Büchi Automata

interpreted over **infinite words** here: over  $\Sigma = \{a, b\}$ 

run: start at some initial state

stepwise: read an input letter, and

traverse the automaton respectively

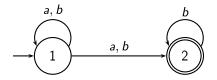
accepting: is infinitely often in a final state while processing

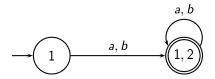
the complete  $\omega$ -word

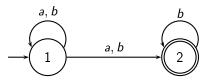
language: words with accepting runs

here:  $\omega$ -words with **finitely many a's** 

### Determinisation of Finite Automata







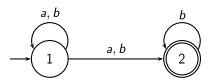
#### Deterministic Büchi Automata ...

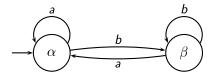
...are less expressive than nondeterministic Büchi automata.

### Example Language: All words with finitely many a's

Construct an input word by repeatedly

- choosing b's until a final state is reached
- choosing an a once.
- ⇒ determinisation requires more involved acceptance condition

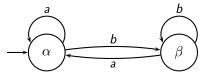




#### Muller Automata

Table of acceptable infinity sets.

finitely many a's:  $\big\{\big\{\beta\big\}\big\}$ 



#### Muller Automata

normal forms

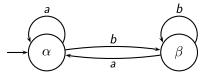
Rabin:

- list of pairs  $(A_i, R_i)$  of accepting and rejecting states
- for some pair, some accepting and no rejecting state occurs infinitely often

- Streett: list of pairs  $(A_i, R_i)$  of accepting and rejecting
  - for all pairs, some accepting or no rejecting

Parity: • priority function

- lowest priority occurring infinitely often is even



#### Muller Automata

normal forms

Rabin:

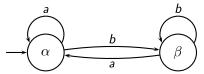
- list of pairs  $(A_i, R_i)$  of accepting and rejecting states
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Streett:

- list of pairs  $(A_i, R_i)$  of accepting and rejecting states (dual case)
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#### Muller Automata

normal forms

Rabin:

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- list of pairs  $(A_i, R_i)$  of accepting and rejecting states (dual case)
- for all pairs, some accepting or no rejecting state occurs infinitely often

Parity:

priority function

 $\mathsf{states} o \mathbb{N}$ 

- lowest priority occurring infinitely often is even
- Rabin chain or Streett double chain condition

# Algorithms

#### determinising $\omega$ -automata

```
1969 Rabin's solution based on deterministing \omega-automata 1988 Safra n^{O(n)} 1988 Michel n^{\theta(n)} (bound by [S08]) 2006 Piterman O(n!^2) (bound by [S08]) 2008 S O((cn)^n) with c\approx 1.65 Rabin 2008 Colcombet and Zdanowski \theta((cn)^n) Rabin 2012 S and Varghese determinising GBA 2014 S and Varghese \theta(n!^2) parity and Streett
```

## Part II

Warm-Up: LTL – Automata & Simple Cases

### Automata & Games

- LTL
- LTL  $\Rightarrow$  alternating word automata  $(\mathcal{A}\mathcal{A})$
- ullet  $\mathcal{A}\mathcal{A}$   $\Rightarrow$  acceptance game for traces
- $\mathcal{A}\mathcal{A} \not\Rightarrow$  existence game for traces
- $\mathcal{NBA} \Rightarrow$  existence game for traces
- ullet  $\mathcal{N}\mathcal{B}\mathcal{A}$  and model checking

# Linear-Time Temporal Logics

- as a word language -

#### LTL formulas

 $\varphi ::= \mathit{true} \mid p \mid \neg \varphi \mid \varphi \land \varphi \mid \varphi \lor \varphi \mid \bigcirc \varphi \mid \Box \varphi \mid \Diamond \varphi \mid \varphi \mathcal{U} \varphi$ 

<b>p</b> :	p									
$\bigcirc \varphi$ :		$\varphi$								
$\Diamond \varphi$ :								$\varphi$		
$\square \varphi$ :	$\varphi$	$\varphi$	φ	φ	φ	φ	φ	φ	$\varphi$	$\varphi$
$\circ \mathcal{U} \psi$ :	φ	φ	φ	φ	φ	φ	φ	φ	ψ	

# Linear-Time Temporal Logics

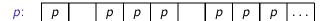
- a backwards aproach -

	0	∨ c	0	$\neg p$
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a harmless tautology

p:	р		р	р	р		р	р	р	
○ <i>p</i> :		$\sqrt{}$	$\sqrt{}$	$\sqrt{}$		$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$
$\bigcirc \neg p$ :	$\sqrt{}$				$\sqrt{}$					
$\bigcirc p \lor \bigcirc \neg p$ :	. /	. /	. /	/	/	/	. /	. /	. /	./
OPVO P.	V	V	_ V	V	$\sqrt{}$	V	$\sqrt{}$	V	V	V
$\Diamond p \lor \bigcirc \neg p$				√ √				<u>√</u>	<u>√</u>	

### Acceptance Game



• the acceptance player can cheat

by using previous choices of the rejection player when constructing a "model"

 the acceptance player can cheat by using previous choices of the rejection player when constructing a "model"

# Acceptance Game

- non-deterministic automata -

$$\bigcirc \bigcirc p \lor \bigcirc \neg p$$

$$\bigcirc \{\Box, \diamondsuit, \bigcirc p \lor \bigcirc \neg p, \bigcirc p, \underline{p}\}$$

$$\bigcirc \{\Box, \diamondsuit, \bigcirc p \lor \bigcirc \neg p, \bigcirc p, \neg p\}$$

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$$\bigcirc \{\Box, \diamondsuit, \underline{p}\}$$

$$\bigcirc \{\Box, \diamondsuit, \underline{p}\}$$

<b>p</b> :	р		р	р	р		р	р	р	
$\mathcal{GBA}$ :	3	2	1	1	3	2	1	1	1	1

- non-deterministic automata -

$$\bigcirc \bigcirc p \lor \bigcirc \neg p$$

$$\bigcirc \{\Box, \diamondsuit, \bigcirc p \lor \bigcirc \neg p, \bigcirc p, p\}$$

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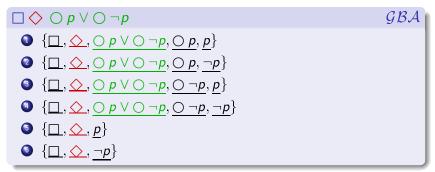
$$\bigcirc \{\Box, \diamondsuit, \bigcirc p \lor \bigcirc \neg p, \bigcirc \neg p, p\}$$

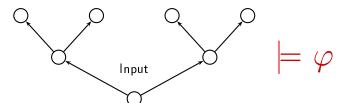
$$\bigcirc \{\Box, \diamondsuit, p\}$$

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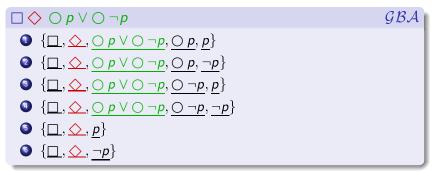
# Model Checking Game

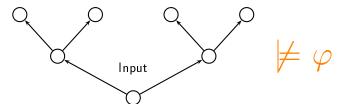
- non-deterministic automata -





- non-deterministic automata -





- non-deterministic automata -

$$\bigcirc \bigcirc p \lor \bigcirc \neg p$$

$$\bigcirc \{\Box, \diamondsuit, \bigcirc p \lor \bigcirc \neg p, \underline{o} p, \underline{p}\}$$

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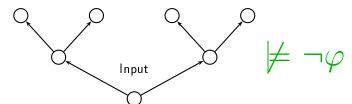
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$$\bigcirc \{\Box, \diamondsuit, \underline{p}\}$$

$$\bigcirc \{\Box, \diamondsuit, \underline{\neg p}\}$$



- non-deterministic automata -

$$\bigcirc \bigcirc p \lor \bigcirc \neg p$$

$$\bigcirc \{\Box, \diamondsuit, \bigcirc p \lor \bigcirc \neg p, \underline{o} p, \underline{p}\}$$

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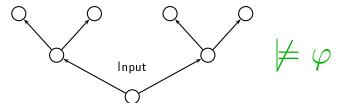
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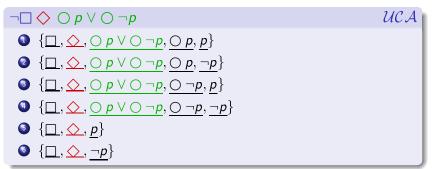
$$\bigcirc \{\Box, \diamondsuit, \underline{o} p \lor \bigcirc \neg p, \underline{\neg p}, \underline{\neg p}\}$$

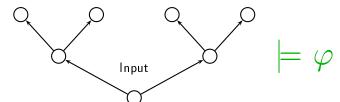
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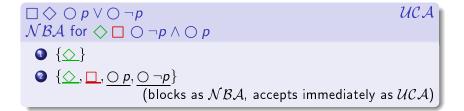


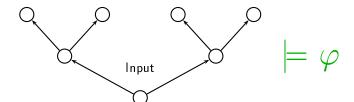
- universal automata -





- universal automata -





### Part III

Automata & Solvability



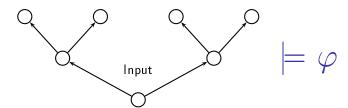
#### Church's Solvability Problem - 1963

Given: an interface specification

(identification of input and output variables)

and a behavioural specification arphi

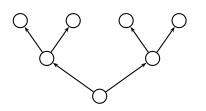
Sought: an implementation ( $\mathit{Input}^* \to \mathit{Output}$ ), satisfying  $\varphi$ 



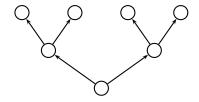
### Automata & Games for Synthesis

**Implementation** 

Computation Tree







#### Automata-theoretic approach

Specification  $\varphi$  ~

Automaton  $\mathcal{A}_{\wp}$ 

Models of  $\varphi$ 

Language of  $\mathcal{A}_{arphi}$ 

Realisability of  $\varphi$   $\sim$ 

Language Non-Emptiness of  ${\cal A}_{arphi}$ 

- on the running example -



as before –  $\mathcal{A}\mathcal{A}$  won't do

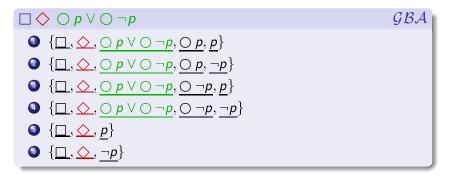
- on the running example -



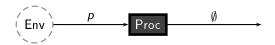
as before –  $\mathcal{A}\mathcal{A}$  won't do how about  $\mathcal{N}\mathcal{A}$ ?

- on the running example -



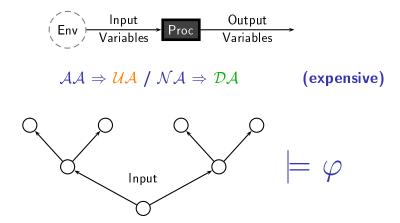


- on the running example -





- incomplete information -



### Extension: Incomplete Information

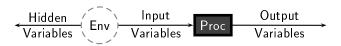
$$\mathcal{U}\mathcal{A} / \mathcal{N}\mathcal{A} \Rightarrow \mathcal{D}\mathcal{A}$$

(expensive)

"narrowing operation"  $\mathcal{A}\mathcal{A}\Rightarrow\mathcal{A}\mathcal{A}$ ,  $\mathcal{U}\mathcal{A}\Rightarrow\mathcal{U}\mathcal{A}$ ,  $\mathcal{N}\mathcal{A}
eq\mathcal{N}\mathcal{A}$ 

- if dir<sub>1</sub> and dir<sub>2</sub> are indistinguishable and
- you'd send  $s_1$  to dir<sub>1</sub> and  $s_2$  to dir<sub>2</sub>
- ightsquigarrow send  $s_1$  and  $s_2$  to dir $_{12}$

### Extension: Incomplete Information



$$\mathcal{U}\mathcal{A} / \mathcal{N}\mathcal{A} \Rightarrow \mathcal{D}\mathcal{A}$$

(expensive)

"narrowing operation"  $\mathcal{A}\mathcal{A} \Rightarrow \mathcal{A}\mathcal{A}$ ,  $\mathcal{U}\mathcal{A} \Rightarrow \mathcal{U}\mathcal{A}$ ,  $\mathcal{N}\mathcal{A} \not\Rightarrow \mathcal{N}\mathcal{A}$ 

- if dir<sub>1</sub> and dir<sub>2</sub> are indistinguishable and
- you'd send  $s_1$  to dir<sub>1</sub> and  $s_2$  to dir<sub>2</sub>
- $\rightarrow$  send  $s_1$  and  $s_2$  to dir<sub>12</sub>

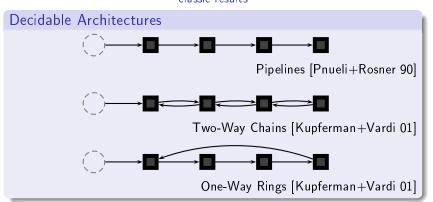
### Part IV

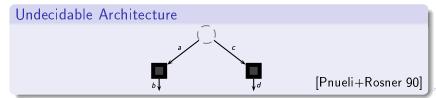
# Distributed Strategies

nowledge information fork synthesis cliff hanger

### Distributed Synthesis

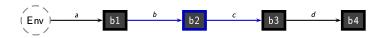
- classic results -







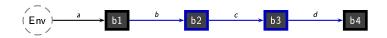
- process b2 knows its input
- process b2 knows its output
- ⇒ process b2 knows the input to process b3
- ⇒ process b2 knows the output of process b3
  - ... least fixed point ⇒ knowledge of b2



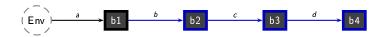
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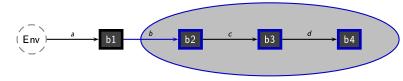


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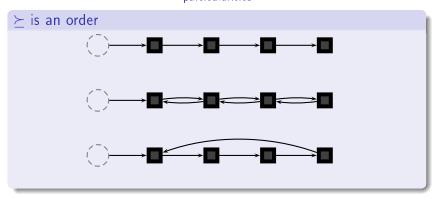
### Super-Processes



- b2 is better informed than b3 and b4 (b2 ≥ b3, b4)
- b2 can simulate b3 and b4
- $\Rightarrow$  b2 can be used as a super-process

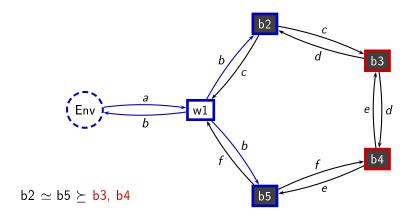
### Decidability of Architectures

particularities –





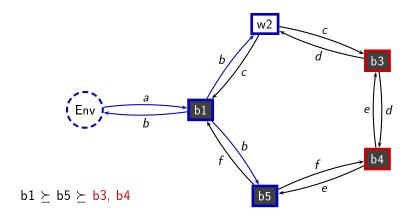
#### Information Fork



## Undecidable



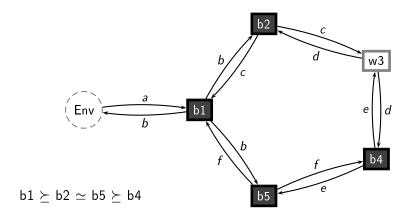
#### Information Fork



## Undecidable



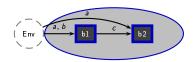
#### No Information Fork



## Decidable

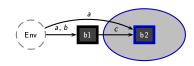


- ordered architecture -

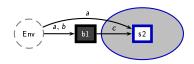


#### ullet ${\cal A}_{arphi}$ accepts strategies for super-process

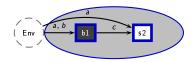
- Automata transformation:  $\mathcal{A}_{arphi}$   $\mathcal{B}_{arphi}$  accepts a strategy for process b2 iff
  - there is a strategy for process b1 such that
  - ullet their composition is accepted by  ${\cal A}_{arphi}$
- ullet test non-emptiness of  $\mathcal{B}_{arphi}$
- ullet  $\mathcal{A}'_{\omega}$  accepts proper strategies for b1
- ullet test non-emptiness of  ${\cal A}'_{arphi}$



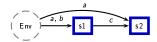
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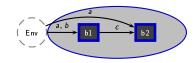
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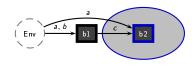


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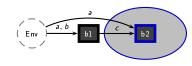
- ullet LTL,  $\mathcal{UWA}$  /  $\mathcal{UTA}$ ,  $\mathcal{DWA}$  /  $\mathcal{DTA}$
- projection ( $\mathcal{N}\mathcal{T}\mathcal{A}$ ), narrowing ( $\mathcal{A}\mathcal{T}\mathcal{A}$ ), non-determinisation  $\mathcal{N}\mathcal{T}\mathcal{A}$ 
  - "annotate" strategy UTA
  - determinise  $\mathcal{D}TA$
  - project strategy -NTA
- ullet test non-emptiness of  $\mathcal{NTA}$  TS /  $\mathcal{DTA}$
- intersect
- test non-emptiness





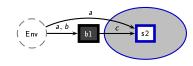
- ullet LTL,  $\mathcal{UWA}$  /  $\mathcal{UTA}$ ,  $\mathcal{DWA}$  /  $\mathcal{DTA}$
- projection  $(\mathcal{NTA})$ , narrowing  $(\mathcal{ATA})$ , non-determinisation  $\mathcal{NTA}$ 
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- LTL, UWA / UTA, DWA / DTA
- projection  $(\mathcal{NTA})$ , narrowing  $(\mathcal{ATA})$ , non-determinisation  $\mathcal{NTA}$ 
  - "annotate" strategy  $\mathcal{UTA}$
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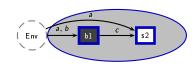


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### Decision Procedure

- ordered architecture -

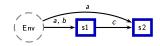


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### Decision Procedure

- ordered architecture -

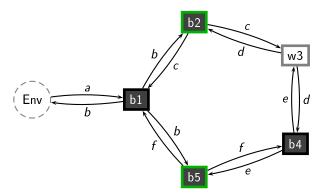


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nowledge information fork **synthesis** cliff hange

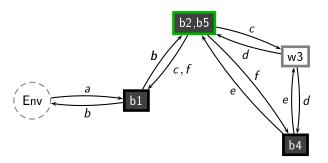
#### Decision Procedure



- merge equivalent processes
- attach white-box processes to better informed process
- remove feedback

knowledge information fork **synthesis** cliff hange

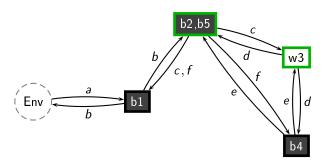
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nowledge information fork **synthesis** cliff hange

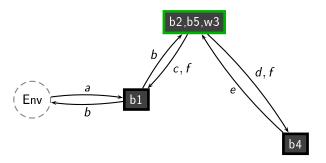
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nowledge information fork **synthesis** cliff hange

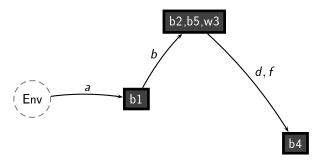
#### Decision Procedure



- merge equivalent processes
- attach white-box processes to better informed process
- remove feedback

knowledge information fork **synthesis** cliff hanger

#### Decision Procedure



#### Ordered Architecture

- decision procedure
- adds one exponent / level of knowledge
- hardness result

nowledge information fork synthesis cliff hanger

## Perfect - But Something 's Wrong

#### Interfaces - friend or foe?

theory: restricted information can be abused

practice: then it is a specification error

#### Infeasible complexity non-elementary, undecidable

ry: completeness result

maximal size of minimal model

practice: no small model ⇒ specification error

#### Redefine realisability

- there is a feasible model
- predefined bounds on the implementation

## ⇒ Bounded Synthesis



nowledge information fork synthesis cliff hanger

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## ⇒ Bounded Synthesis



nowledge information fork synthesis cliff hanger

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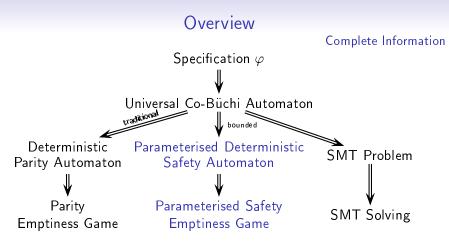
- there is a feasible model
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## ⇒ Bounded Synthesis



### Part V

## Two Steps Towards Practice

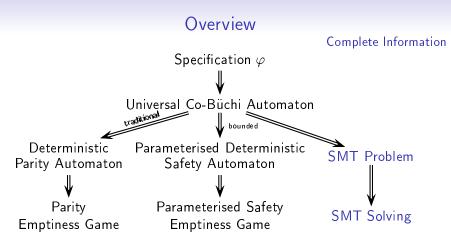


#### Distributed

Sequence of Automata Transformations
Safra-Constructions – Exponential

Locality Constraints Small – Usually Cheap



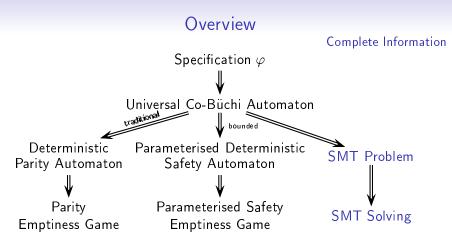


Distributed

Sequence of Automata Transformations
Safra-Constructions – Exponential

Locality Constraints Small – Usually Cheap





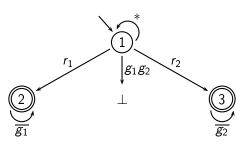
Distributed

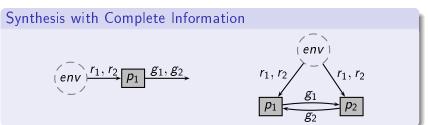
Sequence of Automata Transformations
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Locality Constraints
Small – Usually Cheap

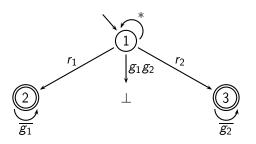


### Example – Simplified Arbiter



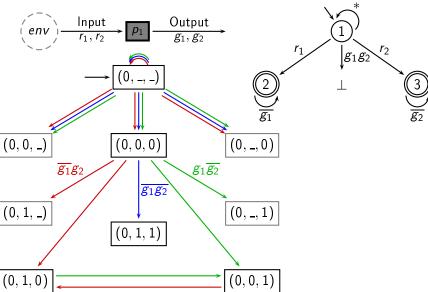


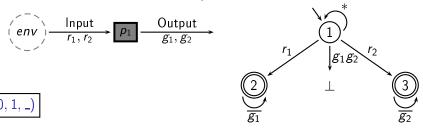
### From Co-Büchi to Safety



#### Realisable specification

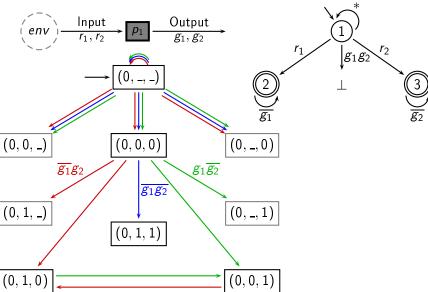
- finite implementation size s
- bound b on the number of rejecting states  $-b \le s \cdot |F|$
- safety condition
- s can be bounded by the size of the resp. deterministic automaton

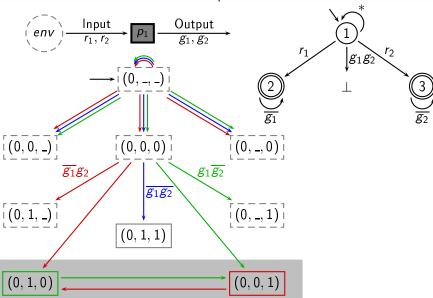




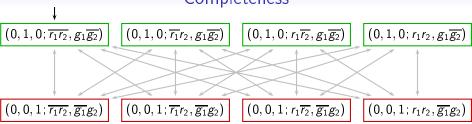
#### Semantics of a Game Positon

- collects the paths of the run tree
- *i*-th position in the annotation:
  - \_: no path ends in automaton-state i
- $n \in \mathbb{N}$ : a path may end in automaton-state i each such path has < n previous visits to rejecting states









#### Theorem – Completeness

An (input preserving) transition system is accepted by a UCB  $\Leftrightarrow$  it has a valid annotation.

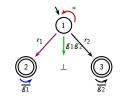
#### Proof idea

Cycle with rejecting state reachable in the run graph 
⇔ no valid annotation.

### Progress Constraints – Automaton Transitions

output complexity: NP-complete





- $\bullet \ \forall t. \, \lambda_1^{\mathbb{B}}(t) \to \neg g_1(t) \vee \neg g_2(t)$
- $\begin{array}{c} \bullet \ \, \forall t. \, \lambda_{1}^{\mathbb{B}}(t) \wedge r_{1}(t) \rightarrow \lambda_{2}^{\mathbb{B}}(\tau_{\overline{\tau_{1}}\overline{\tau_{2}}}(t)) \wedge \lambda_{2}^{\#}(\tau_{\overline{\tau_{1}}\overline{\tau_{2}}}(t)) \geq \lambda_{1}^{\#}(t) \\ \quad \wedge \, \lambda_{2}^{\mathbb{B}}(\tau_{\overline{\tau_{1}}r_{2}}(t)) \wedge \lambda_{2}^{\#}(\tau_{\overline{\tau_{1}}r_{2}}(t)) \geq \lambda_{1}^{\#}(t) \\ \quad \wedge \, \lambda_{2}^{\mathbb{B}}(\tau_{r_{1}\overline{\tau_{2}}}(t)) \wedge \lambda_{2}^{\#}(\tau_{r_{1}\overline{\tau_{2}}}(t)) \geq \lambda_{1}^{\#}(t) \\ \quad \wedge \, \lambda_{2}^{\mathbb{B}}(\tau_{r_{1}r_{2}}(t)) \wedge \lambda_{2}^{\#}(\tau_{r_{1}r_{2}}(t)) \geq \lambda_{1}^{\#}(t) \end{array}$
- $\begin{array}{c} \bullet \ \, \forall t. \, \lambda_{2}^{\mathbb{B}}(t) \wedge \neg g_{1}(t) \rightarrow \lambda_{2}^{\mathbb{B}}(\tau_{\overline{r}_{1}\overline{r}_{2}}(t)) \wedge \lambda_{2}^{\#}(\tau_{\overline{r}_{1}\overline{r}_{2}}(t)) > \lambda_{2}^{\#}(t) \\ \qquad \wedge \, \lambda_{2}^{\mathbb{B}}(\tau_{\overline{r}_{1}r_{2}}(t)) \wedge \lambda_{2}^{\#}(\tau_{\overline{r}_{1}r_{2}}(t)) > \lambda_{2}^{\#}(t) \\ \qquad \wedge \, \lambda_{2}^{\mathbb{B}}(\tau_{\overline{n}\overline{r}_{2}}(t)) \wedge \lambda_{2}^{\#}(\tau_{\overline{n}\overline{r}_{2}}(t)) > \lambda_{2}^{\#}(t) \\ \qquad \wedge \, \lambda_{2}^{\mathbb{B}}(\tau_{\overline{n}\overline{r}_{2}}(t)) \wedge \lambda_{2}^{\#}(\tau_{\overline{n}\overline{r}_{2}}(t)) > \lambda_{2}^{\#}(t) \end{array}$

### **Explicit Synthesis**



#### Church's Solvability Problem - 1963

Given: an interface specification

(identification of input and output variables)

and a behavioural specification arphi

Sought: a **circuit** s.t. (Input\* o Output) satisfies  $\varphi$ 

$$TS \models \varphi$$

CTL: EXPTIME-complete, exponential transition system

LTL: 2EXPTIME-complete, doubly exponential TS



### Explicit vs. Succinct

explicit

transition system Kripke structure

 $2^n$  states

succinct

circuit program online Turing machine

tape size n

min-output PSPACE-complete



min-output PSPACE-complete



min-output PSPACE-complete



LTL: dito for intermediate automata

CTL



only if: guess & verify EXPTIME-complete

hence: PSPACE in the minimal succinct solution

if: much harder uses the  $\mathcal{DSA}$  from bounded synthesis





only if: guess & verify EXPTIME-complete

hence: PSPACE in the minimal succinct solution

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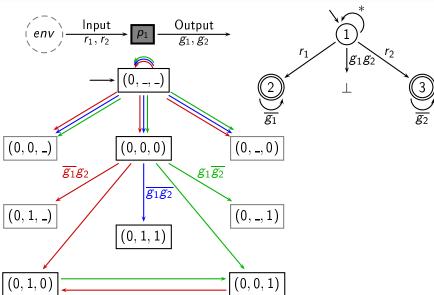
only if: guess & verify EXPTIME-complete

hence: PSPACE in the minimal succinct solution

if: much harder uses the  $\mathcal{DSA}$  from bounded synthesis



### PSPACE=EXPTIME ⇒ Small Model



### Succinct & Fast Synthesis



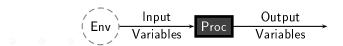


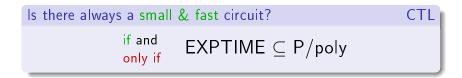
if: as before

only if: • construction not enough
encode universal space bounded ATM
environment provides initial tape
immediate answer to the halting proble



### Succinct & Fast Synthesis



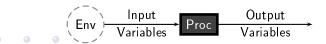


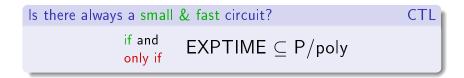
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### Succinct & Fast Synthesis





if: as before

only if: • construction not enough
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### **Implementations**

#### General Search: Genetic Progamming & Co

- Gal Katz, Doron Peled: MCGP: A Software Synthesis Tool Based on Model Checking and Genetic Programming. ATVA 2010: 359-364
  - Gal Katz, Doron Peled: Code Mutation in Verification and Automatic Code Correction. TACAS 2010: 435-450
  - Gal Katz, Doron Peled: Model Checking-Based Genetic Programming with an Application to Mutual Exclusion. TACAS 2008: 141-156
  - Colin G. Johnson: Genetic Programming with Fitness Based on Model Checking. EuroGP 2007: 114-124

### Sneak Preview

Search	mutex		tex	leader election	
Technique		2 shared bits	3 shared bits	3 nodes	4 nodes
simulated annealing	execution time	20	23	84	145
	success rate	19	23	19	17
	overall time	105.26	100	442.1	852.94
hy bri d	execution time	113	171	418	536
	success rate	31	17	15	11
	overall time	364.51	1,005.88	2,786.66	4,872.72
genetic programming	execution time	583	615	1120	1311
	success rate	7	7	3	3
	overall time	8,328.57	8,785.71	37,333.33	43,700.00

Part VII

summary

### Automata Theoretic Approach

#### pro: simple

- narrowing
- projection
- determinisation (word)

### pro: clean

- introduction of Partial Designs
- characterisation of the class of decidable architectures
- uniform synthesis algorithm

con: beyond price

con: does not benefit from small solutions





### **Bounded Synthesis**

#### **Bounded Synthesis**

- guess implementation & verify
- NP complete in minimal transition system

&  $\mathcal{A}_{arphi}$ 

pro: complexity closer to model checking

pro: applicable to distributed systems

con: transition system vs. program / circuit

— is good news —



## Synthesis vs. Model Checking

#### Bounded Synthesis of Succinct Systems

- construct a correct program / circuit
- PSPACE complete in minimal program / circuit

& φ

pro: complexity equal to model checking

pro: applicable to distributed systems

### Summary

- Distributed Synthesis
  - decidability
  - complexity
- Bounded Synthesis
  - decidability
  - complexity
- Succinct Synthesis
  - decidability
  - complexity